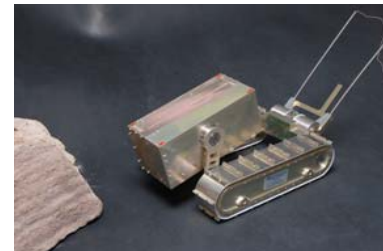
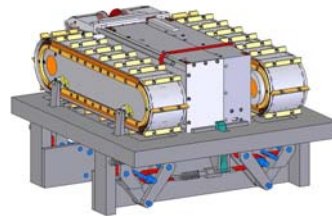
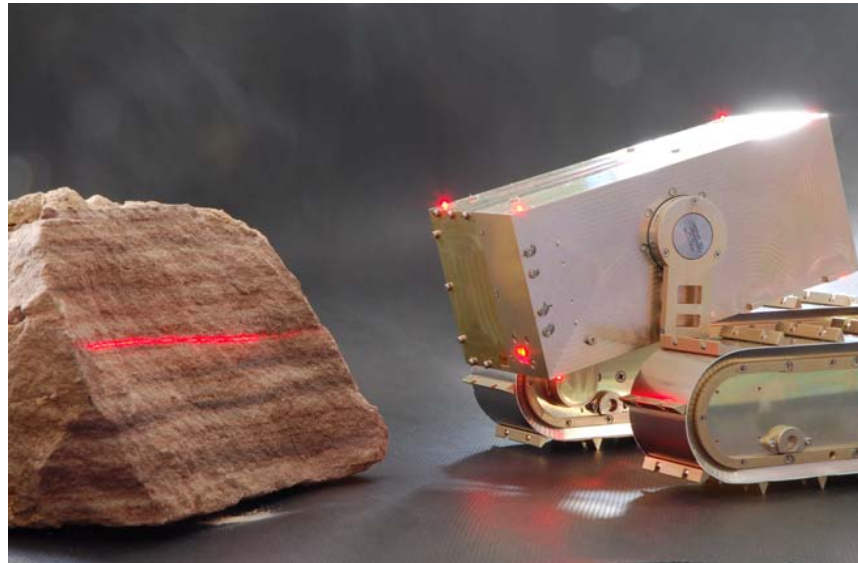


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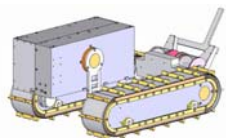
A Micro-Rover for Scientific Exploration in Extreme Environments

- "In-situ" geochemical analysis of various samples on a planetary surface
- Current development optimise for Mercury night side:
 - Surface temperature -183°C:
 - High Vacuum.
 - Fine regolith surface
 - Landing shock 200g in 20ms
- On-surface life time: >14 days
- 2 DOF Payload cabin for climbing & instrument placement
- Payload: Geochemistry Instrument Package Facility (see separate GIPF flyer):
 - APX & Mössbauer Spectrometers:
 - Miniature Imaging system
- Autonomy concept in conjunction with Lander



- Mobility:
 - Overcome obstacles up to: 0.1 m
 - Locomotion speed: 2.7 m/h
 - Total travel distance: >50 m
- Customised locomotion & articulation drives by Harmonic Drive AG
- Electrical Power:
 - During movement: 5.7W peak
 - Other modes: 1.3-3.4W
 - Extendable power & comms tether
- Mass including P/L and module on Lander: <3.2 kg
- Size: < 250 x 160 x 65 mm
- Status:
 - ESA Contract "Mercury Robotic Payload":
 - EM-Model manufacture for Mercury in progress. Environmental testing Q4 2005

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NANOKHOD and other enquiries

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About the company:

von Hoerner & Sulger GmbH is a SME company excelling in the system & detail design and manufacture of specialised scientific instrumentation. For over 30 years the company has built numerous instruments for universities, industries and national & international agencies, 10 of which have successfully flown in space. Please feel free to contact us to discuss any future application that you may have.